

High performance in the smallest of spaces with sophisticated operating and control electronics

The BLDC SN 15 worm geared motor offers maximum performance in the smallest of spaces. It contains sophisticated operating and control electronics. Its other qualities: it is extremely robust, very reliable and particularly quiet.

In the compact motor, the commutation electronics and a digital 4-quadrant speed controller with overcurrent capable output stage, blocking and overload protection are integrated to save space.

The microprocessor-controlled electronics perform a wide range of motor management tasks.

The combination with the precision worm gear SN15 results in an optimal connection. It is available in solid or hollow shaft design with various reduction options.

The gearbox is equipped with ball bearings and lifetime lubrication.

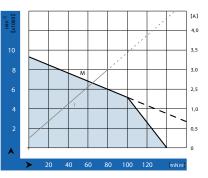
The worm gears are made of special bronze and the steel worms are hardened and ground. This results in less friction and higher efficiency.

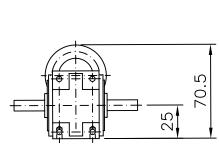
Technical data:

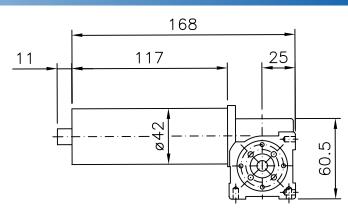
- 3-phase, dynamic internal rotor motor using EC technology with increased starting torque
- Integrated control electronics with powerful microcontroller
- Excellent regulating thanks to the 4-Q PI controller
- High efficiency thanks to the FET final stage
- Analogue target value input
- Overload protection thanks to ar integrated current limiter
- Custom versions available through software and hardware adjustments (e.g. fixed roration speed, direction of rotation)



TECHNICAL DATA







// Characteristics 24 (18 ... 28) V DC Nominal voltage (UBN) Nominal speed (nN) 4000 min⁻¹ Nominal current (IBN) 3,0 A Nominal output power (PN) 40 W 0 ... 10 V Target value input yes Temperature monitoring Overload protection yes IP 40 Protection class Permisible ambient temperature (TU) 0 ... +40 °C

// Motor connection diagram for ECI42 24 V DC PIN-assignment 0 G brown 1 € 9 white 2 0 Poti 10 KOhm blue 3 φblack 4 0 0 yellow 5 direction of rotation 0 0 switch closed

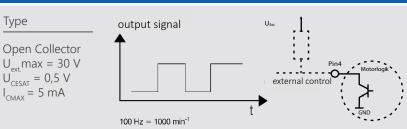
PIN 1 PIN 2 1 direction of rotation PIN 3 GND PIN 4 actual speed drive PIN 5 setpoint input

PIN 2 1 Direction of rotation left 0 Direction of rotation right	Pin2
low (0) 0 0,8 V high (1) 2,4 28 V	
Direction of rotation seen on shall	ft. GND

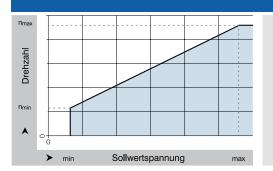
1. Control input direction of rotation (PIN,,)

// Fill assignment connector type	
Lumberg	Type RKT 5-228 /m (straight connector)
	Type RKWT 5-228 /m (corner connector)
	Type FST 5-FKT 5-293 /m (Fixcon plug / connector)

2. Actual value output (PIN 4)



Pin5 O



Speed setting for speed control by means of

3. Setpoint input (PIN 5)

setpoint voltage Interface 0 ... 10 V DC. (1 V = \sim 400 U/min)

At setpoint voltage <0.2 V, braking operation is activated. The braking function is only used to brake the drives. It is not a holding function for drive standstill.

